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Applicant(s): David W. Nesbitt

AUTOMATED ROUTE DETERMINATION

300A

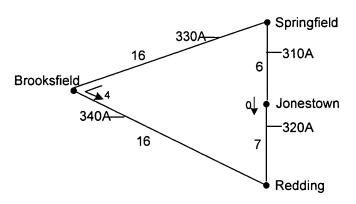


FIG. 3A

<u>300</u>

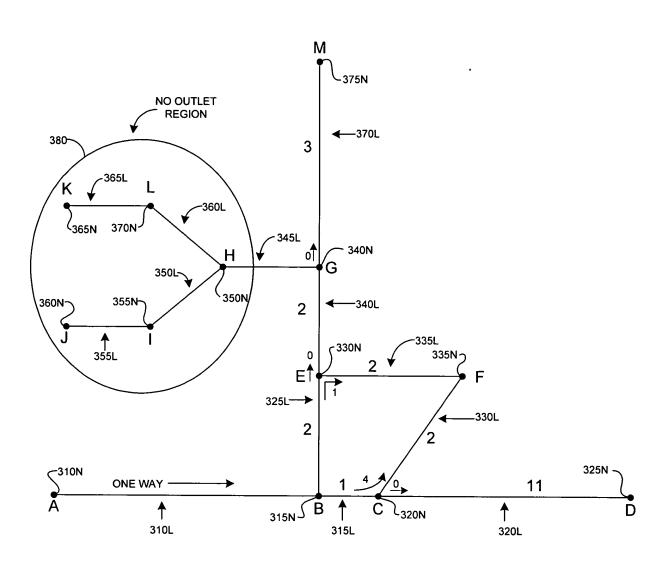


FIG. 3

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Applicant(s): David W. Nesbitt

AUTOMATED ROUTE DETERMINATION

<u>400</u>

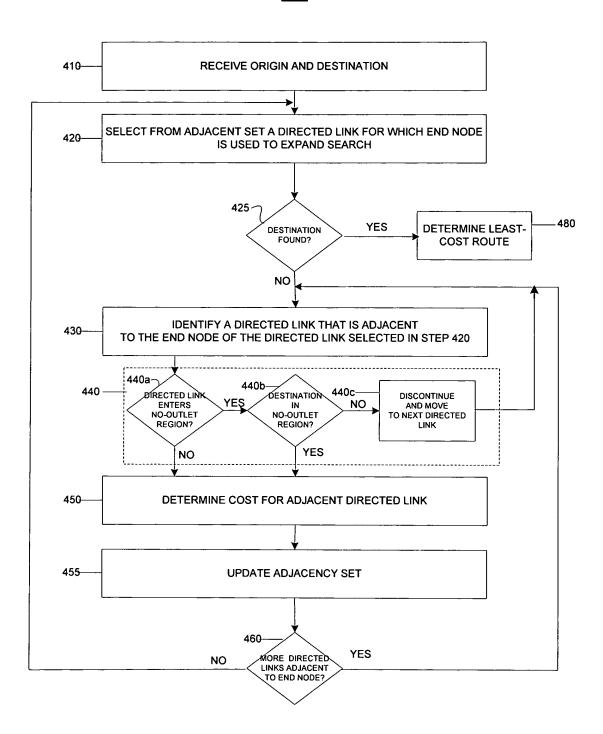


FIG. 4

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Applicant(s): David W. Nesbitt
AUTOMATED ROUTE DETERMINATION

	520	DONE	DIRECTED LINK	BC	BE	EG				
200				↑	1	↑				
	510	ADJACENCY SET	DIRECTED LINK COST	—	2	4	2	7	7	- 2
			TRAVEL ALONG DIRECTED LINK	_	2	2	2	2	ε,	
			INTERSEC -TION COST	0	0	0	-	4	0	0
			COST TO PREVIOUS DIRECTED LINK	0	0	2	2	-	4	τ-
			PREVIOUS DIRECTED LINK			BE	BE	ВС	EG	ВС
			DIRECTED	BC	BE	EG	EF	CF	GM	CD
				530	532	542	545	540	250	535

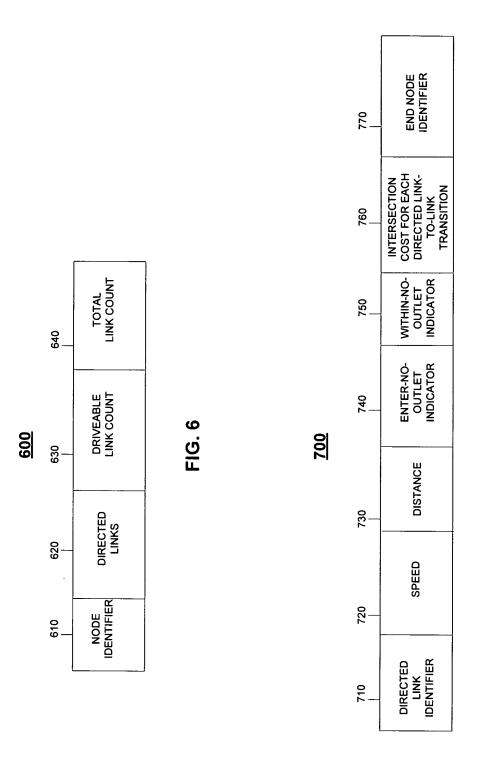


FIG. 7

Applicant(s): David W. Nesbitt
AUTOMATED ROUTE DETERMINATION

<u>800</u>

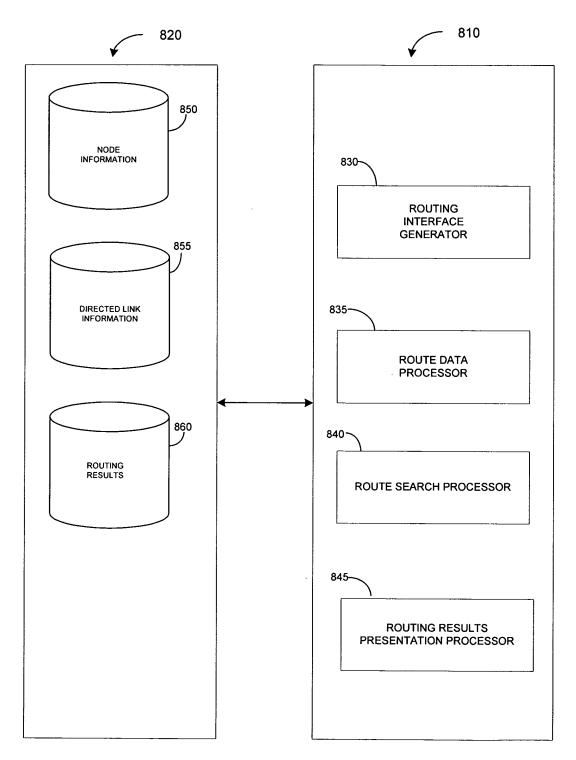


FIG. 8

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Applicant(s): David W. Nesbitt AUTOMATED ROUTE DETERMINATION

<u>440</u>

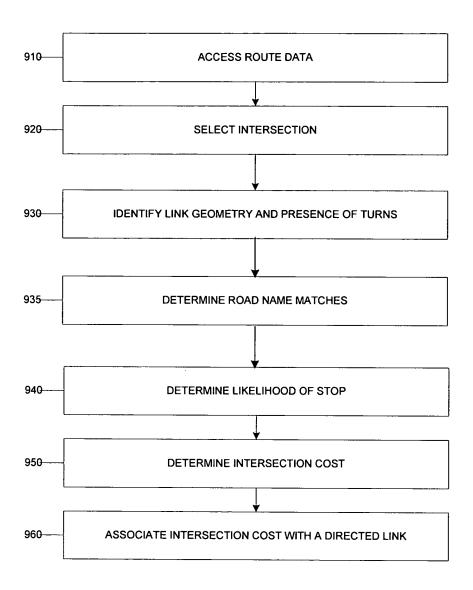


FIG. 9

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Applicant(s): David W. Nesbitt
AUTOMATED ROUTE DETERMINATION

<u>450</u>

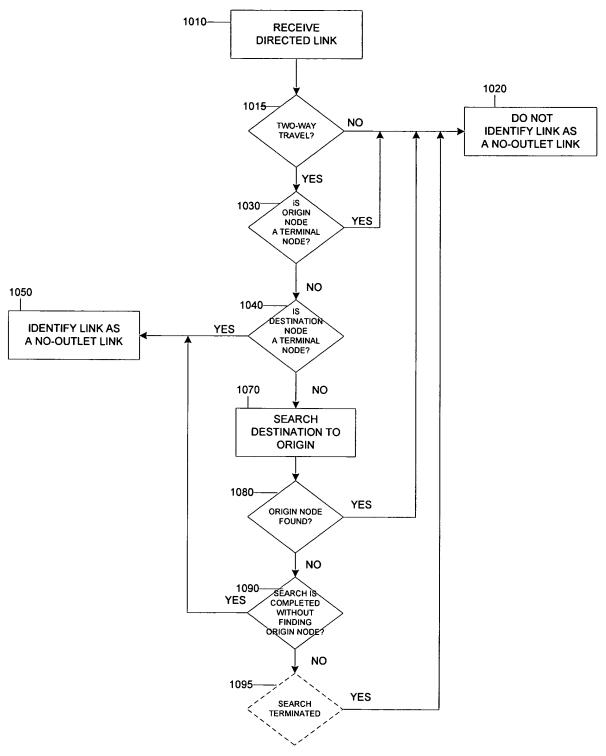


FIG. 10